WHAT IS CLAIMED IS:

1	1. An automated detection algorithm to compute the ring profile of colon
2	like surfaces comprising the steps of:
3	providing an original image of a colon like surface disposed along a major
4	axis in a scan having vertex points, each vertex point having a discrete point identifier and
5	three dimensional position information;
6	generating a thin version of the colon like surface utilizing neighbors
7	averaging of the three dimensional position information for every vertex point in the original
8	colon view;
9	modeling the thin version of the colon like surface with an ordered set of 3-D
10	points to produce a curve proximate to the major axis of the colon like surface;
11	isolating segments of vertex points (along) between planes normal to the curve
12	proximate to the major axis of the colon from the thin version of the colon like surface;
13	mapping the isolated segments of vertex points from the thin version of the
14	colon like surface back to the original image of the colon like surface to generate a ring
15	profile of the colon like surface.
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1	2. The automated detection algorithm to compute the ring profile of colon
2	like surfaces according to claim 1 comprising the steps of:
3	decimating the vertex points of the provided original image.
1	3. The automated detection algorithm to compute the ring profile of colon
2	like surfaces according to claim 1 comprising the steps of:
3	computing a centerline of the colon utilizing the ring profile of the colon like
4	surface.
_	4. The automated detection algorithm to compute the ring profile of colon
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2	like surfaces according to claim 3 comprising the steps of:
3	measuring along the computed centerline of the colon like surface to
4	determine positional information relative to the colon like surface.
1	 The automated detection algorithm to compute the ring profile of colon
2	like surfaces according to claim 3 comprising the steps of:
3	computing a smoothed version of the centerline of the colon to approximate
4	centerlines obtained by invasive colonoscopy.

1	6. The automated detection algorithm to compute the ring profile of color
2	like surfaces according to claim 3 comprising the steps of:
3	utilizing the ring profile along a preselected length of the computed colon
4	centerline to determine the local colon volume and local colon distension along the
5	preselected length of the colon.
1	7. The automated detection algorithm to compute the ring profile of color
2	like surfaces according to claim 3 comprising the steps of:
3	mapping the vertices distance to the computed centerline; and,
4	building an image of vertices distances to centerline to map the colon.
1	8. The automated detection algorithm to compute the ring profile of color
2	like surfaces according to claim 3 comprising the steps of:
3	mapping the vertices distance to the computed centerline to obtain a mapped
4	centerline view of the colon;
5	rotating the mapped centerline view of the colon to spatially reorient the
6	mapped centerline view of the colon; and,
7	reconstructing a spatially reoriented image of the colon from the rotated
8	centerline view by expanding the vertices distances to map the colon.
1	9. An automated detection algorithm to compute the ring profile of colon
2	like surfaces comprising the steps of:
3	providing an original image of the colon like surfaces disposed along a major
4	axis in a scan having the colon like surface identified by vertex points, each of vertex point
5	having a discrete point identifier and three-dimensional positional information;
6	generating a thinned image of the colon like surface utilizing a neighbors
7	averaging of the three-dimensional positional information for vertex points in the original
8	colon view;
9	randomly designating a first vertex modeling point at a vertex point along the
10	thinned the colon image;
11	identifying and marking neighboring vertex points to the randomly selected
12	first vertex modeling point;
13	designating a second vertex modeling point located at a predetermined
14	distance from the first of vertex modeling point;

15	sequentially repeating the identifying and marking, and designating steps to
16	designate vertex modeling points from the randomly selected first vertex modeling point to
17	an end of the colon;
18	connecting the designated vertex modeling points to produce a curve
19	proximate to the major axis of the colon like surface;
20	isolating groups of vertex points between planes normal to the curve from the
21	thin image of the colon like surface; and,
22	mapping the isolated groups of a vertex points from the thinned image of the
23	colon like surface back to the original image of the colon like surface to generate a ring
24	profile of the colon like surface.
1	10. An automated detection algorithm to compute an approximate
2	centerline profile of colon like surfaces comprising the steps of:
3	providing an original image of the colon like surfaces disposed along a major
4	axis in a scan having the colon like surface identified by vertex points, each of vertex point
5	having a discrete point identifier and three-dimensional positional information;
6	generating a thinned image of the colon like surface utilizing a neighbors
7	averaging of the three-dimensional positional information for vertex points in the original
8	colon view;
9	randomly designating a first vertex modeling point at a vertex point along the
10	thinned the colon image;
11	identifying and marking neighboring vertex points to the randomly selected
12	first vertex modeling point;
13	designating a second vertex modeling point located at a predetermined
14	distance from the first of vertex modeling point;
15	sequentially repeating the identifying and marking, and designating steps to
16	designate vertex modeling points from the randomly selected first vertex modeling point to
17	an end of the colon;
18	connecting the designated vertex modeling points to produce a curve
19	proximate to the major axis of the colon like surface.
1	11. An automated detection algorithm to compute the ring profile of colon
2	like surfaces comprising the steps of:
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3	providing an original image of the colon like surfaces disposed along a major
4	axis in a scan having the colon like surface identified by vertex points, each of vertex point
5	having a discrete point identifier and three-dimensional positional information;
6	generating a thinned image of the colon like surface utilizing a neighbors
7	averaging of the three-dimensional positional information for vertex points in the original
8	colon view;
9	randomly designating a first vertex modeling point at a vertex point along the
10	thinned the colon image;
11	identifying and marking neighboring vertex points to the randomly selected
12	first vertex modeling point;
13	designating a second vertex modeling point located at a predetermined
14	distance from the first of vertex modeling point;
15	sequentially repeating the identifying and marking, and designating steps to
16	designate vertex modeling points from the randomly selected first vertex modeling point to
17	an end of the colon;
18	connecting the designated vertex modeling points to produce a curve
19	proximate to the major axis of the colon like surface;
20	isolating groups of vertex points between planes normal to the curve from the
21	thin image of the colon like surface; and,
22	mapping the isolated groups of a vertex points from the thinned image of the
23	colon like surface back to the original image of the colon like surface to generate a ring
24	profile of the colon like surface.
1	12. An automated detection algorithm to compute an approximate
2	centerline profile of colon like surfaces comprising the steps of:
3	providing an original image of the colon like surfaces disposed along a major
4	axis in a scan having the colon like surface identified by vertex points, each of vertex point
5	having a discrete point identifier and three-dimensional positional information;
6	generating a thinned image of the colon like surface utilizing a neighbors
7	averaging of the three-dimensional positional information for vertex points in the original
8	colon view;
9	randomly designating a first vertex modeling point at a vertex point along the
10	thinned the colon image;

11	identifying and marking neighboring vertex points to the randomly selected
12	first vertex modeling point;
13	designating a second vertex modeling point located at a predetermined
14	distance from the first of vertex modeling point;
15	sequentially repeating the identifying and marking, and designating steps to
16	designate vertex modeling points from the randomly selected first vertex modeling point to
17	an end of the colon;
18	connecting the designated vertex modeling points to produce a curve
19	proximate to the major axis of the colon like surface.